

A HAYDEN PUBLICATION

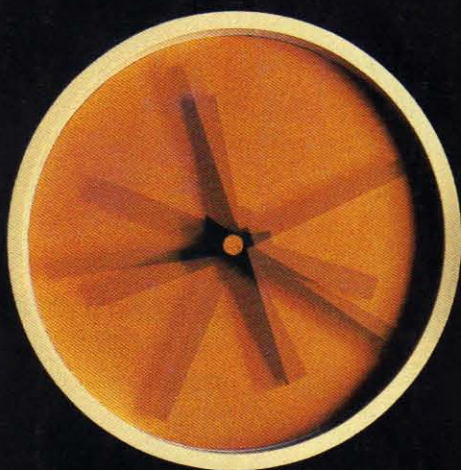
INTERNATIONAL

ElectronicDesign[®]

DESIGNERS AND ENGINEERING MANAGERS — WORLDWIDE

DECEMBER 27, 1984

Designer's Reference: Software standards remain elusive for CAE, networks
Global Computer Survey: Users look for a wide variety of improvements
Graphics workstation sculpts 3D models with high resolution, brilliant color



**GaAs RAM
creates cache
that cycles
at half
the speed
of light**



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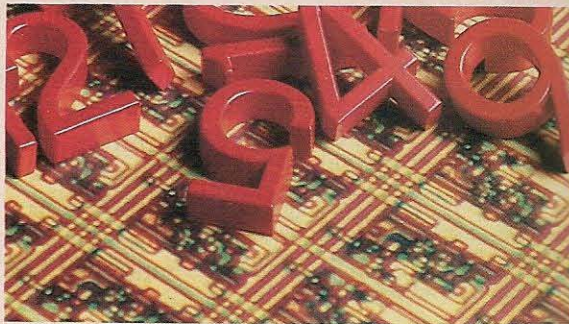
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Software tool generates test programs for GPIB in hours, not weeks

With little or no programming skill, designers can create software for bus-driven test equipment. An interactive menu does the trick.

Workstation scores high on programmability, speed, and power

Simple support software, coupled to hardware op codes, speeds the job of programming a VAX-like system with a brilliant display.

Like logic analyzers, 1-GHz scope triggers on specific patterns

A host of triggering options lets an instrument hunt down glitches, arming it with a scope's sharp eyes and a logic analyzer's brain.

Design Solution: Mastering a programming language spells better software

Developing efficient code requires a familiarity with the internal workings of a language. Here PL/M-86 is put to work for the iAPX 86 microprocessors.

Design Solutions:

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TI-59 program finds elliptic transfer function for low-pass filters.

Five-transistor amplifier boosts fast pulses into 50- Ω coaxial cable.

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Cover photograph by David Wagner
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NEW PRODUCTS

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stable condition in the Z80's daisy-chained interrupt priority structure, the circuit has been designed so that an interrupt status signal cannot change when the Machine Cycle 1 line, \overline{M}_1 , is low.)

An active-low interrupt request signal (\overline{INT}) from the support chip is sent to the CPU system through IC_5 , an inverter, to indicate the start of the cycle. The interrupt acknowledge line (INTA) from the 8086 or 8088 system is connected to the clock inputs of dual flip-flops IC_{1A} and IC_{1B} , as well as to an OR gate, IC_3 . Therefore, when the first INTA pulse ends, \overline{M}_1 goes

low. At the start of the second pulse, the I/O Request line (IORQ) also goes low. The requesting device with the highest priority is allowed to place its interrupt vector on the data bus and set an internal latch that indicates the interrupt is under service.

At the end of the second pulse, the Q_2 output from flip-flop IC_{1B} goes low, resetting IC_{1B} , as well as \overline{M}_1 and IORQ. A third flip-flop, IC_{2A} , samples the Q_2 output from IC_{1B} and resets the latter device at the end of the cycle. The length of the reset pulse is determined by the frequency of the clock used by IC_{2A} .

TI-59 program finds elliptic transfer function for low-pass filters

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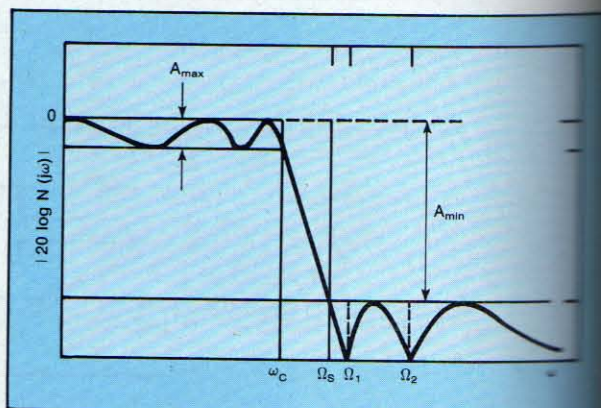
Of all filtering functions, the elliptic transfer function is among the most useful because of its steep fall-off at the band edges (see the figure). A program designed for the TI-59 calculator can help evaluate the function by finding the odd-order poles and zeros of a low-pass filter (see the program). The algorithm calculates several things:

- The transmission zeros— ΩK , where $K = 1, 2, \dots, (N-1)/2$;
- The minimum attenuation at the stop band with respect to the maximum value at the pass band A_{\min} expressed in dB;

- The real poles (P_0);
- The complex-conjugate poles (P_K)

The conjugate poles are equal to $\alpha_K + j\beta_K$, where α_K is the real part and β_K is the imaginary part of the K^{th} pole.

Data supplied by the user (Table 1) includes the order of the filter (that is, the number of poles, or N); the cut-off frequency (ω_c), expressed



A calculator program determines the poles and zeros of an elliptic transfer-function filter, one characterized by its steep fall-off at the band edges.

ed in radians/s; the stop-band frequency (Ω_s), expressed in radians/s; and either the reflection coefficient (ρ), shown as a percentage, or the maximum attenuation of the pass-band ripple in dB (A_{max}).

The last two of those parameters are related to each other by the formula:

$$A_{max} = -10 \log \left[1 + \left(\frac{\rho}{100} \right)^2 \right]$$

Once the poles and the zeros have been found, the transfer function, $H(s)$, is found with the help of the formula:

$$H(s) = \frac{(S^2 + \Omega_1^2)(S^2 + \Omega_2^2) \dots (S^2 + \Omega_{(n-1)/2}^2)}{(S + P_0)(S + P_1)(S + P_1^*) \dots (S + P_{(n-1)/2})(S + P_{(n-1)/2}^*)}$$

The results obtained with the calculator program for a normalized low-pass filter—that is, one with a ω_c of 1—compare favorably with those found in other filter tables (Table 2). Values other than unity can be used. The program, which can be recorded on a magnetic card, can evaluate the elliptic transfer filtering function up to the 21st order.

*S. Darlington, "Simple Algorithms for Elliptic Filters and Generalizations Thereof," *IEEE Transactions on Circuits and Systems*, Vol. CAS-25, No. 12, pp. 975-980, 1978.

Table 1. User instructions for low-pass elliptic transfer function

Step	Procedure	Enter	Press		Display
1	Filter order	n	A		n
2	Pass-band cut-off frequency (rad/s)	ω_c	B		ω_c
3	Stop-band frequency (rad/s)	Ω_s	C		Ω_s
4a	Either reflection coefficient (%) or passband ripple (dB)	ρ	D		0
4b		A_{max}	E		0
5	Compute transmission zeros, Ω_k $k = 1, 2, \dots, (n-1)/2$			R/S	Ω_k
	Repeat step 5 for each value of k until 0 appears in the display.				
6	Compute stop-band attenuation, A_{min}		2nd	C'	A_{min}
7	Compute real pole, P_0	0	2nd	D'	P_0
8a	Compute k^{th} pole, real part	k	2nd	D'	Re (P_k)
8b	Compute k^{th} pole, imaginary part		2nd	E'	Im (P_k)
	Repeat steps 8a and 8b for each value of k				
	$k = 1, \dots, (n-1)/2$				

Table 2. Results of calculation for a low-pass filter

Input	Zeros	Output
		Real and complex poles
n = 5	$\Omega_1 = 1.465436966$	$P_0 = -0.3186089933$
$\omega_c = 1$	$\Omega_2 = 1.656220908$	$P_1 = -0.2095320012 + j 0.6875524702$
$\Omega_s = 1.414213562$	$\Omega_3 = 2.165997414$	$P_2 = -0.0582836518 + j 0.9913678402$
$\rho = 50\%$	$\Omega_4 = 3.944466518$	
	$A_{min} = 51.4064495 \text{ dB}$	

TI-59 program for filter transfer function

000	76	LBL	065	43	RCL	130	95	=	195	04	4	260	95	=
001	11	A	066	08	08	131	39	CDS	196	04	4	261	34	FX
002	42	STD	067	91	R/S	132	55	+	197	42	STD	262	65	+
003	10	10	068	76	LBL	133	43	RCL	198	54	54	263	43	RCL
004	04	4	069	14	D	134	15	15	199	04	4	264	01	01
005	42	STD	070	55	+	135	95	=	200	42	STD	265	35	1/X
006	02	02	071	01	1	136	35	1/X	201	02	02	266	95	=
007	01	1	072	00	0	137	76	LBL	202	02	2	267	65	X
008	02	2	073	00	0	138	34	FX	203	45	YX	268	43	RCL
009	42	STD	074	95	=	139	71	SBR	204	53	(269	46	46
010	59	59	075	33	X ²	140	61	GTO	205	43	RCL	270	95	=
011	43	RCL	076	94	+/-	141	97	DSZ	206	10	10	271	71	SBR
012	10	10	077	85	+	142	02	02	207	75	-	272	24	CE
013	91	R/S	078	01	1	143	34	FX	208	01	1	273	65	X
014	76	LBL	079	95	=	144	72	ST*	209	54)	274	43	RCL
015	12	B	080	28	LOG	145	56	56	210	65	X	275	45	45
016	42	STD	081	65	X	146	35	1/X	211	43	RCL	276	95	=
017	07	07	082	01	1	147	65	X	212	15	15	277	71	SBR
018	91	R/S	083	00	0	148	43	RCL	213	45	YX	278	24	CE
019	76	LBL	084	95	=	149	09	09	214	43	RCL	279	65	X
020	13	C	085	94	+/-	150	95	=	215	10	10	280	43	RCL
021	42	STD	086	76	LBL	151	01	1	216	95	=	281	44	44
022	08	08	087	15	E	152	44	SUM	217	42	STD	282	65	X
023	55	+	088	55	+	153	57	57	218	43	43	283	02	2
024	43	RCL	089	01	1	154	01	1	219	76	LBL	284	95	=
025	07	07	090	00	0	155	44	SUM	220	22	INV	285	55	+
026	95	=	091	95	=	156	56	56	221	71	SBR	286	43	RCL
027	34	FX	092	22	INV	157	43	RCL	222	75	-	287	43	43
028	42	STD	093	28	LOG	158	57	57	223	72	ST*	288	95	=
029	11	11	094	75	-	159	32	X/T	224	54	54	289	35	1/X
030	43	RCL	095	01	1	160	43	RCL	225	32	X/T	290	71	SBR
031	08	08	096	95	=	161	10	10	226	01	1	291	24	CE
032	65	X	097	34	FX	162	22	INV	227	44	SUM	292	45	YX
033	43	RCL	098	42	STD	163	67	EQ	228	54	54	293	43	RCL
034	07	07	099	01	01	164	35	1/X	229	32	X/T	294	10	10
035	95	=	100	00	0	165	00	0	230	97	DSZ	295	35	1/X
036	34	FX	101	70	RAD	166	91	R/S	231	02	02	296	95	=
037	42	STD	102	01	1	167	76	LBL	232	22	INV	297	42	STD
038	09	09	103	06	6	168	17	B*	233	43	RCL	298	53	53
039	43	RCL	104	42	STD	169	43	RCL	234	01	01	299	43	RCL
040	11	11	105	56	56	170	10	10	235	33	X ²	300	06	06
041	76	LBL	106	00	0	171	42	STD	236	65	X	301	91	R/S
042	85	+	107	42	STD	172	03	03	237	43	RCL	302	76	LBL
043	33	X ²	108	57	57	173	01	1	238	47	47	303	19	D*
044	42	STD	109	76	LBL	174	07	7	239	45	YX	304	65	X
045	58	58	110	35	1/X	175	42	STD	240	04	4	305	89	π
046	33	X ²	111	04	4	176	56	56	241	95	=	306	95	=
047	75	-	112	42	STD	177	76	LBL	242	85	+	307	55	+
048	01	1	113	02	02	178	45	YX	243	01	1	308	43	RCL
049	95	=	114	01	1	179	73	RC*	244	95	=	309	10	10
050	34	FX	115	04	4	180	56	56	245	35	1/X	310	95	=
051	85	+	116	42	STD	181	65	X	246	28	LOG	311	42	STD
052	43	RCL	117	48	48	182	43	RCL	247	65	X	312	02	02
053	58	58	118	43	RCL	183	09	09	248	01	1	313	00	0
054	95	=	119	57	57	184	95	=	249	00	0	314	42	STD
055	72	ST*	120	65	X	185	91	R/S	250	95	=	315	01	01
056	59	59	121	89	π	186	02	2	251	94	+/-	316	36	PGM
057	32	X/T	122	95	=	187	44	SUM	252	42	STD	317	05	05
058	01	1	123	55	+	188	56	56	253	06	06	318	17	B*
059	44	SUM	124	53	(189	97	DSZ	254	43	RCL	319	65	X
060	59	59	125	02	2	190	03	03	255	01	01	320	43	RCL
061	32	X/T	126	65	X	191	45	YX	256	33	X ²	321	53	53
062	97	DSZ	127	43	RCL	192	91	R/S	257	35	1/X	322	95	=
063	02	02	128	10	10	193	76	LBL	258	85	+	323	42	STD
064	85	+	129	54)	194	18	D*	259	01	1	324	50	50

(continued on p. 239)

(continued from p. 238)

TI-59 program for filter transfer function

325	32	X:IT	353	76	LBL	381	85	+	409	42	STD	437	22	INV
326	65	X	354	10	E'	382	01	1	410	04	04	438	44	SUM
327	43	RCL	355	43	RCL	383	95	=	411	36	PGM	439	52	52
328	53	53	356	51	51	384	34	FX	412	04	04	440	92	RTN
329	95	=	357	65	X	385	85	+	413	10	E'	441	76	LBL
330	42	STD	358	43	RCL	386	43	RCL	414	36	PGM	442	61	GTO
331	51	51	359	11	11	387	05	05	415	04	04	443	42	STD
332	05	5	360	95	=	388	95	=	416	17	B'	444	49	49
333	42	STD	361	91	R/S	389	92	RTN	417	73	RC*	445	35	1/X
334	00	00	362	76	LBL	390	76	LBL	418	52	52	446	85	+
335	01	1	363	75	-	391	54)	419	65	X	447	43	RCL
336	05	5	364	42	STD	392	43	RCL	420	02	2	448	49	49
337	42	STD	365	55	55	393	50	50	421	95	=	449	95	=
338	52	52	366	35	1/X	394	42	STD	422	35	1/X	450	55	+
339	76	LBL	367	85	+	395	01	01	423	42	STD	451	02	2
340	53	(368	43	RCL	396	43	RCL	424	03	03	452	95	=
341	71	SBR	369	55	55	397	51	51	425	00	0	453	55	+
342	54)	370	95	=	398	42	STD	426	42	STD	454	73	RC*
343	97	DSZ	371	55	+	399	02	02	427	04	04	455	48	48
344	00	00	372	02	2	400	36	PGM	428	36	PGM	456	95	=
345	53	(373	95	=	401	05	05	429	04	04	457	32	X:IT
346	43	RCL	374	34	FX	402	15	E	430	13	C	458	01	1
347	50	50	375	92	RTN	403	43	RCL	431	42	STD	459	22	INV
348	65	X	376	76	LBL	404	50	50	432	50	50	460	44	SUM
349	43	RCL	377	24	CE	405	42	STD	433	32	X:IT	461	48	48
350	11	11	378	42	STD	406	03	03	434	42	STD	462	32	X:IT
351	95	=	379	05	05	407	43	RCL	435	51	51	463	92	RTN
352	91	R/S	380	33	X ²	408	51	51	436	01	1			

Five-transistor amplifier boosts fast pulses into 50-Ω coaxial cable

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A simple five-transistor pulse amplifier delivers 5-V pulses into a 50-Ω load, with rise times of just 2.6 ns and fall times of 3.5 ns, matching the performance of more costly circuits containing more parts. Simply by vary-

ing the supply voltage over a range of 6 to 14 V and adjusting the circuit's off-board attenuator, the pulse amplitude can be reduced to as little as 100 mV.

The circuit (see the figure) works from dc to 50 MHz and will deliver pulses as short as 10 ns. It is driven by a TTL signal through a 740S00 quad Schottky NAND gate, IC_A through IC_D. However, only an ECL-level signal is available, a level translator, such as the MC10125, can be substituted for the 74S00.

Transistor Q₁, wired as a common-emitter